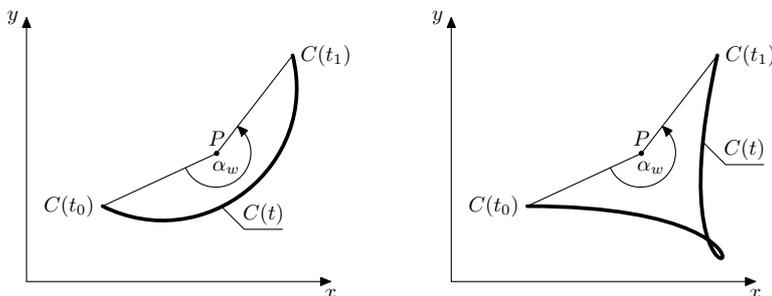


# ON COMPUTING A WINDING NUMBER FOR BÉZIER SPLINES

Bogusław Jackowski

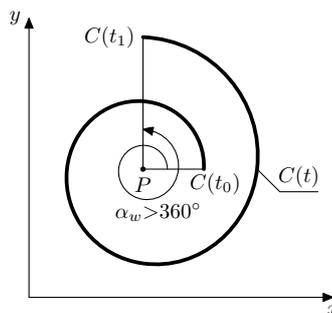
Assume that we have given a point  $P$  in the plane and the planar curve  $C(t)$  defined for  $t_0 \leq t \leq t_1$ . The total angle encircled by the radius  $PC(t)$  as  $t$  runs from  $t_0$  to  $t_1$  we will call the *winding angle* and denote by  $\alpha_w$ :



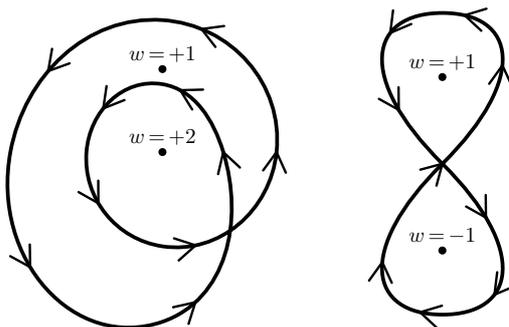
Note that the winding angle is insensitive to certain local properties of the curve  $C(t)$  (e.g., local loops): in the figures above, the *winding angle* is the same in both cases (it is assumed that points  $P$ ,  $C(t_0)$  and  $C(t_1)$  coincide).

The winding angle is positive if the the point  $P$  lies to the right with respect to the point traversing the curve, and negative otherwise.

Of course, the absolute value of a winding angle can be larger than  $360^\circ$ :



For cyclic curves, the *winding angle* is always a multiple of  $360^\circ$ , i.e.,  $\alpha_w = 360^\circ w$ , where  $w$  is an integer. The entity  $w$  is called the *winding number* (for a given point and curve).



In the sequel, we will focus our attention on cyclic Bézier splines.

The idea of the algorithm computing the *winding number* for Bézier splines is due to Laurent C. Siebenmann (metafont@ens.fr, 2000; now the MetaPost Discussion List is hosted by TUG—metapost@tug.org). Siebenmann’s solution, however, was MetaPost-oriented—it exploited heavily the operation *arctime*, available in MetaPost but unavailable, e.g., in MetaFont. Below, I’ll present an algorithm basing on the same idea but referring to more elementary properties of a Bézier segment.

For a given point  $P$  and a Bézier spline  $C$ , we will try to find the *winding angle* by measuring the *winding angles* for a discrete series of time points. First, we will try to measure angles between nodes  $0, 1, 2, \dots, n$  of the spline  $C$ . If the relevant Bézier segments are appropriately short, the sum of the angles yields the total *winding angle*. The problem arises, when the Bézier arc is too long—see, e.g., the leftmost panel of the first figure (the angle  $C(t_0)PC(t_1)$  equals  $360^\circ - \alpha_w$ ).

The main observation of Siebenmann is as follows: if the length of the subarc  $C(t)$  for  $t_0 \leq t \leq t_1$  is shorter than the length of the longer of the radii  $PC(t_0)$  and  $PC(t_1)$ , then we can safely assume that the (acute) angle between  $PC(t_0)$  and  $PC(t_1)$  is the *winding angle*. Actually, we do not need to know the exact length of the arc—an approximation suffices. If  $B_a, B_b, B_c$ , and  $B_d$  are points defining a Bézier arc  $B$  (i.e.,  $B_a$  and  $B_d$  are its nodes,  $B_b$  and  $B_c$  are its control points), then

$$|B_a B_b| + |B_b B_c| + |B_c B_d| \geq |B|$$

( $|\dots|$  denotes the length of an interval and the length of a Bézier arc). In other words, we can safely use the left-hand side of the above inequality instead of the true value of the arc length in the computation of the *winding angle/number*.

The algorithm can be expressed in a “pseudocode” as follows:

```

input: a point  $P$  and a Bézier spline  $B$ , consisting of segments  $B_1, B_2, \dots, B_n$ 
output:  $\alpha_w$  – the winding angle for  $P$  and  $B$ 
procedure windingangle( $P, B$ )
  if  $B$  is a single segment
    let  $B_a, B_b, B_c, B_d$  be the consecutive control nodes of the segment  $B$ 
    if  $\min(|PB_a|, |PB_d|) < \text{assumed minimal distance}$ 
      exit ( $P$  almost coincides with  $B$ , winding angle incalculable)
    fi
    if  $|B_a B_b| + |B_b B_c| + |B_c B_d| > \max(|PB_a|, |PB_d|)$ 
      return windingangle( $P, B(0, 1/2)$ ) + windingangle( $B(1/2, 1)$ )
    else
      return angle  $\alpha$  between the radii  $PB_a$  and  $PB_d$  ( $-90^\circ < \alpha < 90^\circ$ )
    fi
  else
    return windingangle( $P, B_1$ ) +  $\dots$  + windingangle( $P, B_n$ )
  fi
end

```

An example of MetaPost/MetaFont implementation is given below:

```

1  vardef mock_arclength(expr B) = % |B| -- B\`ezier segment
2  % |mock_arclength(B)| >= arclength(B) |
3  length((postcontrol 0 of B)-(point 0 of B)) +
4  length((precontrol 1 of B)-(postcontrol 0 of B)) +
5  length((point 1 of B)-(precontrol 1 of B))
6  enddef;

7  vardef windingangle(expr P,B) = % |P| -- point, |B| -- B\`ezier spline
8  if length(B)=1: % single segment
9    save r,v;
10   r0=length(P-point 0 of B); r1=length(P-point 1 of B);
11   if (r0<2eps) and (r1<2eps): % MF and MP are rather inaccurate, we'd better stop now
12     errhelp "It is rather not advisable to continue. Will return 0.";
13     errmessage "windingangle: point almost coincides with B\`ezier segment (dist="
14       & decimal(min(r0,r1)) & ")";
15     0
16   else:
17     v:=mock_arclength(B); % |v| denotes both length and angle
18     if (v>r0) and (v>r1): % possibly too long B\`ezier arc
19       windingangle(P, subpath (0, 1/2) of B) + windingangle(P, subpath (1/2, 1) of B)
20     else:
21       v:=angle((point 1 of B)-P)-angle((point 0 of B)-P);
22       if v>=180: v:=v-360; fi if v<-180: v:=v+360; fi
23       v
24     fi
25   fi
26 else: % multisegment spline
27   windingangle(P,subpath (0,1) of B)
28   for i:=1 upto length(B)-1: + windingangle(P,subpath (i,i+1) of B) endfor
29 fi
30 enddef;

```

Note that although the returned angle (line 23 in the MF/MP code above) is acute, the difference of the component angles (line 21) can be outside the interval  $(-180^\circ, 180^\circ)$ ; hence the normalization (line 22).

If the operation *windingnumber* is needed for some reasons, it can be implemented trivially:

```
vardef windingnumber (expr P,B) = % |P| -- point, |B| -- B\`ezier spline
  windingangle(P,B)/360
enddef;
```

The operations *windingangle* or, equivalently, *windingnumber* can be used, e.g., for determining the mutual position of two nonintersecting cyclic curves (whether one is embeded inside the other or not):

```
tertiarydef a inside b =
  if path a: % |and path b|; |a| and |b| must be cyclic and must not touch each other
    begingroup
      save a_,b_; (a_,b_)=(windingnumber(point 0 of a,b), windingnumber(point 0 of b,a));
      (abs(a_-1)<eps) and (abs(b_-)<eps)
    endgroup
  else: % |numeric a and pair b|
    begingroup
      (a>=xpart b) and (a<=ypart b)
    endgroup
  fi
enddef;
```

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*Postscriptum. In some cases, another definition, equivalent to the one formulated above may be useful (the formulation, given below without a proof of equivalence, is a slightly edited excerpt from the Laurent C. Siebenmann’s email):*

Assume that there are given curve  $C$  and point  $P$ . Choose at random a line segment emanating from the point  $P$  to the point  $W$ , with  $W$  outside the bounding box of  $C$  and  $P$ . Inductively examine the intersection points  $Q$  of  $PQ$  with  $C$ . Supposing these points  $Q$  are all “nondegenerate” intersections, they are also finite in number, and a sign  $+1$  or  $-1$  is associated to each. Nondegenerate means that  $Q$  is a smooth point of  $c$  and the tangent vector  $T$  to  $C$  at  $Q$  is not parallel to  $PQ$ , and that  $Q$  is not a point where  $C$  crosses itself. The sign to use is the sign of the wedge product ‘ $(Q - P)$  wedge  $T$ ’, i.e.,

$$(Q - P) \cdot (T \text{ rotated } -90)$$

The sum of the signs is the *winding number*.

It is a probabilistic theorem that degenerate intersections will rarely be met.